



上海交通大学
SHANGHAI JIAO TONG UNIVERSITY



Chapter 6

Hidden Markov Models

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- **Introduction to Hidden Markov Model**
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 - **Hidden Markov Models**
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Reading

- Rabiner, L.(1989) A Tutorial on Hidden Markov Models and Selected Applications in Speech Recognition. Proceedings of the IEEE, 77 (2) 257-286
- Rabiner, L., and Juang, Biing-Hwang, (1993), Fundamentals of Speech Recognition, Prentice Hall.



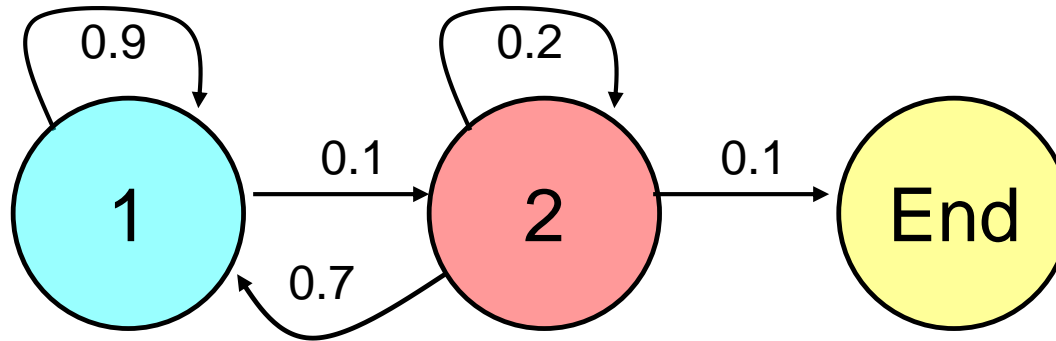
Markov chain: a process that the current state depends on at most a limited number of previous states

- **Weather**
 - Sunny, Rain, Rain, Sunny, Cloudy, Cloudy,....
- **Stock market index**
 - Up, up, down, down, down, up, up, up,
- **Girl/Boy friend's mood**
 - High, low, low, high, high, high, ...
- **Genome sequence**
 - ATGTTAGATATAACAGATAA
- **Flip coins**
 - HTTTHHHHHH



Hidden Markov Model

HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHTTHTTTTTHTHHHHTHTH

Observed sequence x

11221111122221111112222

Hidden state sequence π

$$\pi^* = \arg \max_{\pi} P(x, \pi)$$



Hidden Markov Model

- **Elements of an HMM (N, M, A, B, Init)**

1. **N: number of states in the model**

- $S = \{S_1, S_2, \dots, S_N\}$, and the state at time t is q_t .

2. **M: alphabet size (the number of observation symbols)**

- $V = \{v_1, v_2, \dots, v_M\}$

3. **A: state transition probability distribution**

- $A = \{a_{ij}\}$ where $a_{ij} = P[q_{t+1} = S_j | q_t = S_i]$, $1 \leq i, j \leq N$

4. **E: emission probability**

- $E = \{e_j(k)\}$ (observation symbols probability distribution in state j), where $e_j(k) = P[v_k \text{ at } t | q_t = S_j]$, $1 \leq j \leq N$, $1 \leq k \leq M$

5. **Init: initial state probability**

- $\text{Init} = \{I_i\}$, where $I_i = P[q_1 = S_i]$, $1 \leq i \leq N$.



HMM is a generative model

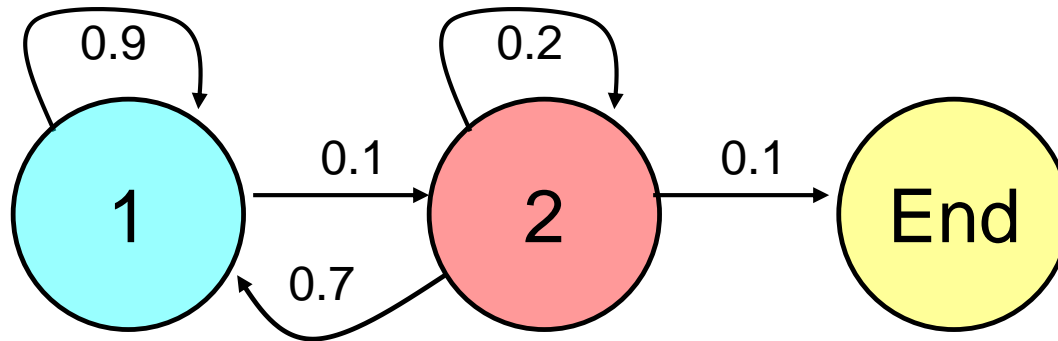
HMM can be used as a generator to produce an observation sequence $O=O_1O_2\dots O_T$, where each O_t is one of the symbols from V , and T is the number of observations in the sequence.

1. Choose an initial state $q_1=S_i$ according to Init;
2. Set $t=1$;
3. Choose $O_t=v_k$ according to $e_i(k)$ (the symbol probability distribution in state S_i);
4. Transit to a new state $q_{t+1}=S_j$ according to a_{ij} ;
5. Set $t=t+1$; return to step 3 if $t<T$; otherwise terminate the procedure.



HMM is a generative model

HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHTTHTTTTTHTHHHHHTHTH

Observed sequence x

11221111122221111112222

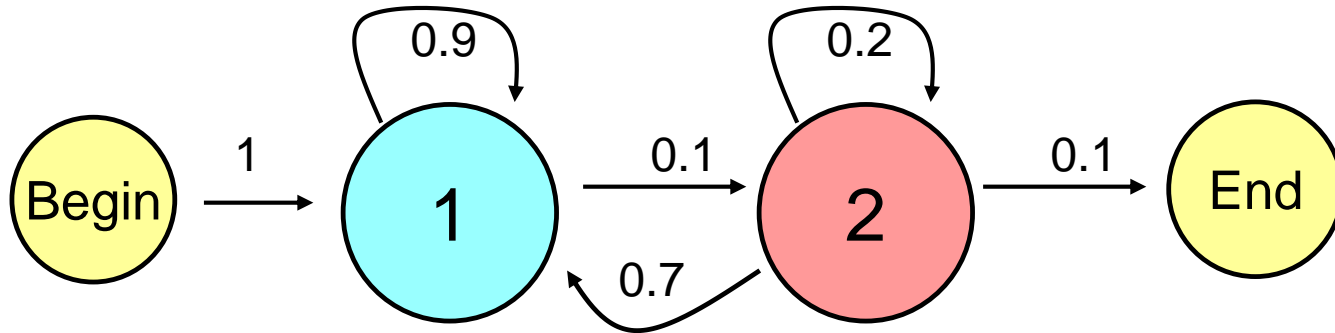
Hidden state sequence π

$$P(x, \pi | \lambda) = \text{Init}_{\pi_0} * e_{\pi_0}(x(0)) * \prod_{0 \leq i \leq T} (a_{\pi_i \pi_{i+1}} e_{\pi_{i+1}}(x(i)))$$



HMM is a generative model

HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHT Observed sequence x

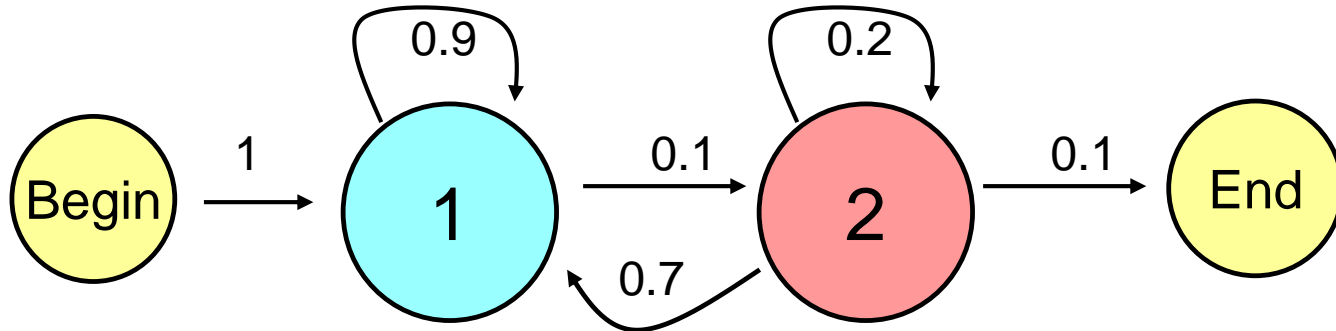
11221 Hidden state sequence π

$$P(x, \pi \mid \lambda) = ?$$



HMM is a generative model

HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHT Observed sequence x

11221 Hidden state sequence π

$$\begin{aligned} P(x, \pi | \lambda) &= \text{Init}_{\pi_0} * e_{\pi_0}(x(0)) * \prod_{0 \leq i \leq T} (a_{\pi_i \pi_{i+1}} e_{\pi_{i+1}}(x(i))) \\ &= 1 * e_1(T) * (a_{11} e_1(T)) * (a_{12} e_2(H)) * (a_{22} e_2(H)) * (a_{21} e_1(T)) \\ &= 1 * 0.2 * (0.9 * 0.2) * (0.1 * 0.3) * (0.2 * 0.3) * (0.7 * 0.2) \end{aligned}$$



Hidden Markov Model

⊙ HMM: $\lambda = \{A, B, \text{Init}\}$

⊙ Three basic problems for HMMs

1. Given the observation sequence $O = O_1 O_2 \dots O_T$, and a model $\lambda = \{A, B, \text{Init}\}$, how to compute $P(O | \lambda)$?
2. Given the observation sequence $O = O_1 O_2 \dots O_T$, and a model $\lambda = \{A, B, \text{Init}\}$, how to choose a corresponding state sequence $Q = q_1 q_2 \dots q_T$, which is optimal in some meaningful sense..
3. How to estimate model parameters $\lambda = \{A, B, \text{Init}\}$ to maximize $P(O | \lambda)$.

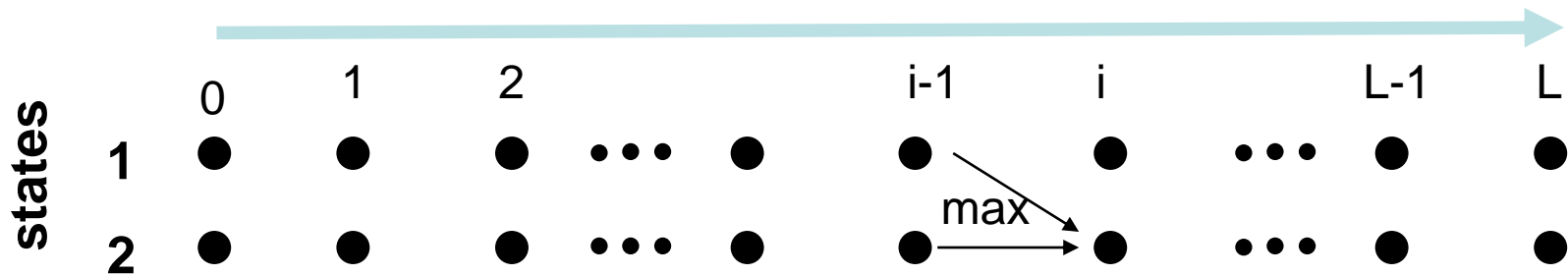


Hidden Markov Model

- ④ **HMM: $\lambda = \{A, B, \text{Init}\}$**
- ④ **Three basic problems for HMMs**
 1. **From the observation sequence and the model to a joint probability;**
 2. **Find the best hidden state sequence;**
 3. **Optimize the model parameters;**



Most Probable Path and Viterbi Algorithm



Let
$$f_l(i) = \max_{\{\pi_0, \dots, \pi_{i-1}\}} (\Pr(x_0, \dots, x_{i-1}, x_i, \pi_0, \dots, \pi_{i-1}, \pi_i = l))$$

Recursion ($i=1 \dots L$)

$$f_l(i) = e_l(x_i) \max_k (f_k(i-1) a_{kl});$$

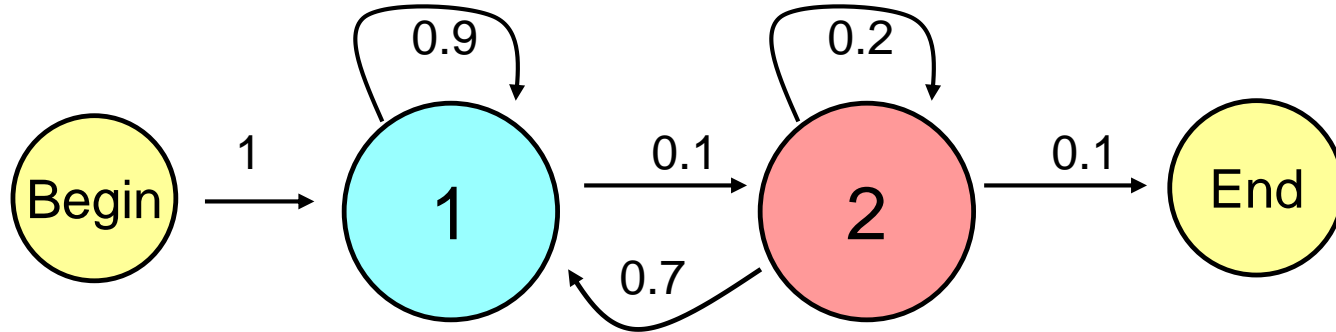
$$ptr_i(l) = \arg \max_k (f_k(i-1) a_{kl}).$$

Time complexity $O(N^2L)$ space complexity $O(NL)$

Solution to problem 2: prob of best state sequence



Viterbi for the HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHT

Observed sequence x

11221

Hidden state sequence π

T

T

H

H

T

0

1

2

3

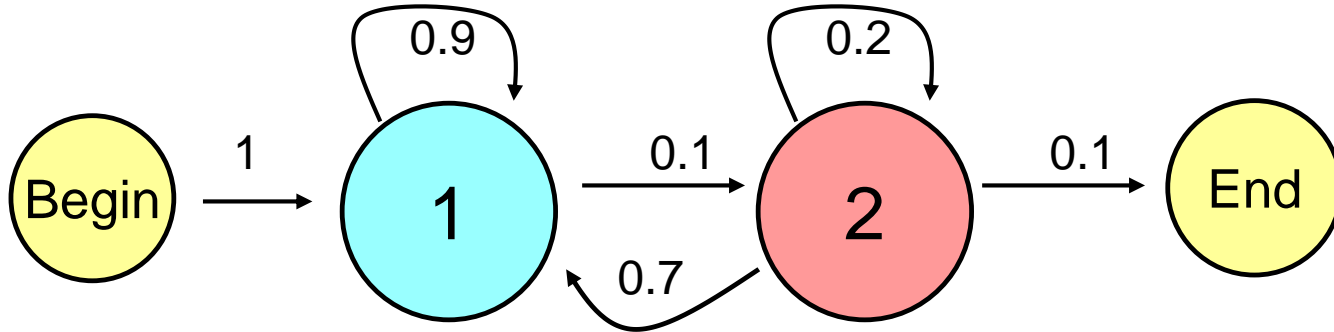
4

1

2



Viterbi for the HMM for two biased coins flipping



$$e_1(H) = 0.8, e_1(T) = 0.2, e_2(H) = 0.3, e_2(T) = 0.7$$

TTHHT

Observed sequence x

11221

Hidden state sequence π

T

T

H

H

T

0

1

2

3

4

1

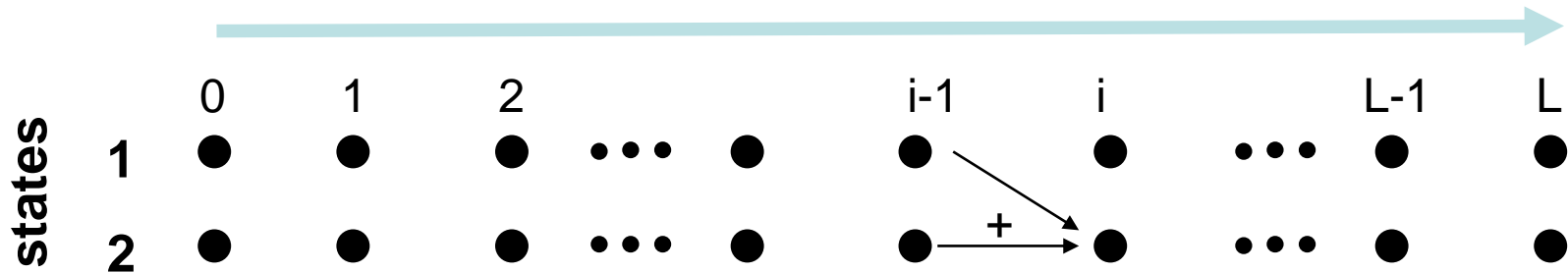
0.2 $\text{Max} 0.2 * (0.9 * 0.2, 0) = 0.036$ $\text{max} 0.8 * (0.036 * 0.9, 0.014 * 0.7) = 0.0259$ $\text{Max } 0.8 * (0.0259 * 0.9, 0.0108 * 0.7) = 0.018662$ $= \text{max} 0.2 * (0.018662 * 0.9, 0.000777 * 0.7) = 0.003359$

2

0 $\text{Max} 0.7 * (0.2 * 0.1, 0) = 0.014$ $\text{Max} 0.3 * (0.036 * 0.1, 0.014 * 0.2) = 0.0108$ $\text{Max} 0.3 (0.0259 * 0.1, 0.0108 * 0.2) = 0.000777$ $= \text{max} 0.3 (0.018662 * 0.1, 0.000777 * 0.7) = 0.0005599$



Probability of All the Possible Paths and Forward Algorithm



Let $f_l(i) = \Pr(x_0, \dots, x_i, \pi_i = l)$

Initialization ($i=1 \dots L$) $f_0(i) = \pi_i e_i(x_0)$

Recursion ($i=1 \dots L$) $f_l(i) = e_l(x_i) \sum_k (f_k(i-1) a_{kl})$

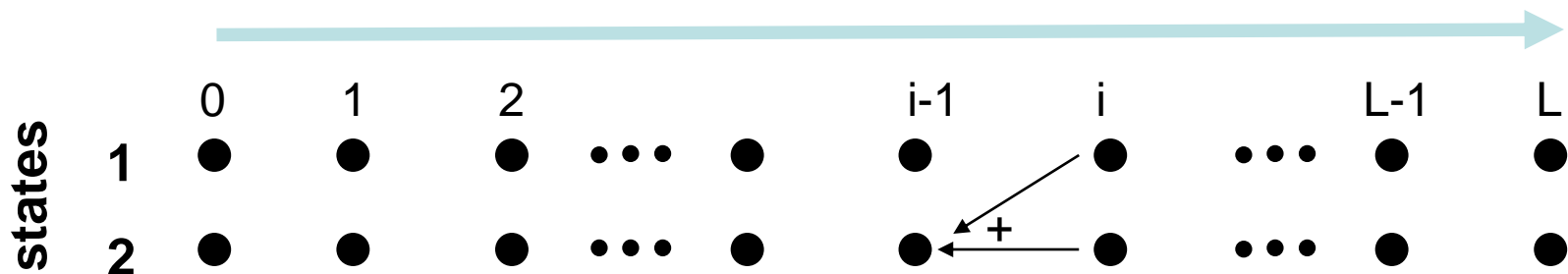
Probability of all the
probable paths

$$P(x) = \sum_{\pi} P(x, \pi) = \sum_k f_k(L)$$

Solution to problem 1



Posterior Probability and Forward and Backward Algorithm

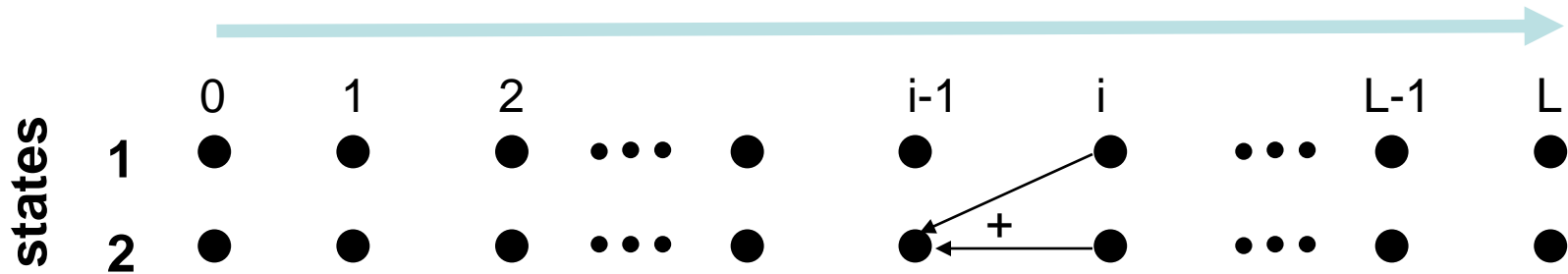


Posterior Probability

$$P(\pi_i = k | x) = \frac{P(\pi_i = k, x)}{P(x)}$$



Backward Algorithm



Let $b_k(i) = \Pr(x_{i+1}, x_{i+2}, \dots, x_L, \pi_i = k)$

Initialization ($i=1 \dots L$) $b_L(i) = 1, \quad 1 \leq i \leq N$

Recursion ($i=1 \dots L$) $b_l(i) = \sum_k (a_{lk} e_k(x_i)) b_{l+1}(i),$

$l = L-1, L-2, \dots, 0; 1 \leq i \leq N$

Probability of all the probable paths

$$P(x) = \sum_{\pi} P(x, \pi) = \sum_k b_k(0)$$



Optimize the model parameters

- ④ **HMM: $\lambda = \{A, B, \text{Init}\}$**
- ④ **With annotations**
 - **Maximum likely-hood**
- ④ **Without annotations**
 - **EM algorithm**



Optimize the model parameters

⊙ **HMM: $\lambda = \{A, B, \text{Init}\}$, Without annotations**

Baum-Welch method (EM method)

Let $\xi_l(i, j) = P(\pi_l = i, \pi_{l+1} = j \mid x, \lambda)$

then $\xi_l(i, j) = \frac{f_l(i) a_{ij} e_j(x_{l+1}) b_{l+1}(j)}{\sum_i \sum_j (f_l(i) a_{ij} e_j(x_{l+1}) b_{l+1}(j))}$

Let $\gamma_l(i) = \sum_{j=1}^N \xi_l(i, j)$

then $\sum_{l=0}^N \gamma_l(i)$ = expected number of transitions from S_i

$\sum_{l=0}^N \xi_l(i, j)$ = expected number of transition S_i to S_j



Optimize the model parameters(2)

• HMM: $\lambda = \{A, B, \text{Init}\}$, Without annotations

Baum-Welch method (EM method)

Then, $\overline{\text{Init}}_i =$ expected frequency in S_i at time 0 = $\gamma_0(i)$

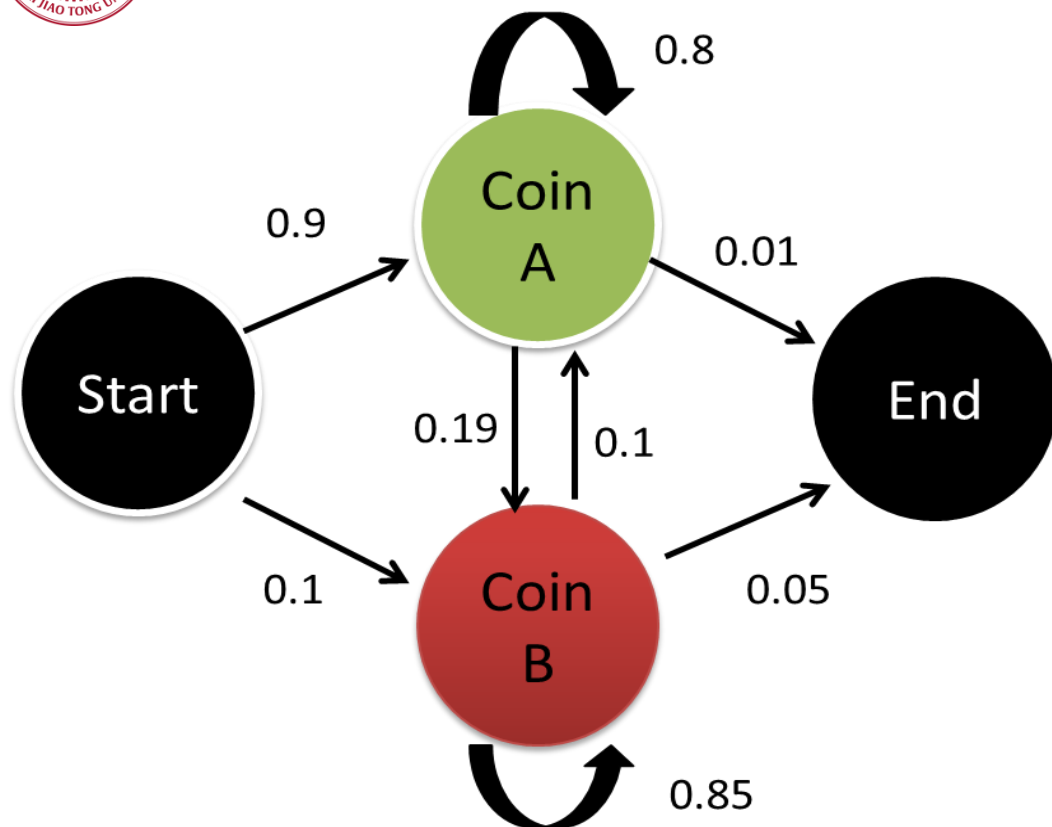
$$a_{i,j} = \frac{\text{expected number of transitions from } S_i \text{ to } S_j}{\text{expected number of transitions from } S_i} = \frac{\sum_{l=0}^{L-1} \xi_l(i, j)}{\sum_{l=0}^{L-1} \gamma_l(i)}$$

$$e_i(k) = \frac{\text{expected number of times in state } i \text{ and observing symbol } v_k}{\text{expected number of times in state } i} = \frac{\sum_{l=0}^L \gamma_l(i)}{\sum_{l=0}^L \gamma_l(i)} \quad \text{s.t. } x_l = v_k$$

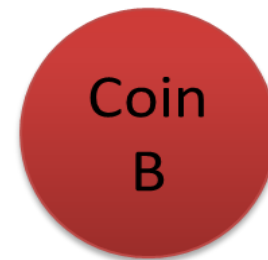


One more example:

Flipping two coins



H: 0.5
T: 0.5



H: 0.2
T: 0.8

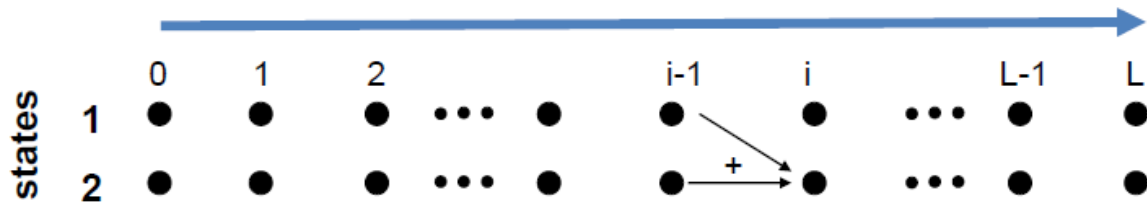
⊗ $O = \text{HHTHHTTTHT}, P(O|\lambda) = ?$

Problem 1: Given the observation sequence $O = O_1 O_2 \dots O_T$, and a model $\lambda = \{A, B, \text{Init}\}$, how to compute $P(O | \lambda)$, the probability of the observation sequence given the model?



Forward Algorithms

	H	H	T	H	H	T	T	T	H	T	Emd
A	0.45	0.181	0.073 42	0.031 44	0.013 06	0.053 71	0.023 45	0.001 11	5.817 e-4	2.580 e-4	2.42 3e-5
B	0.02	0.0205	0.041 45	0.009 83	0.002 86	0.003 94	0.003 49	0.002 73	5.067 e-4	4.329 e-4	

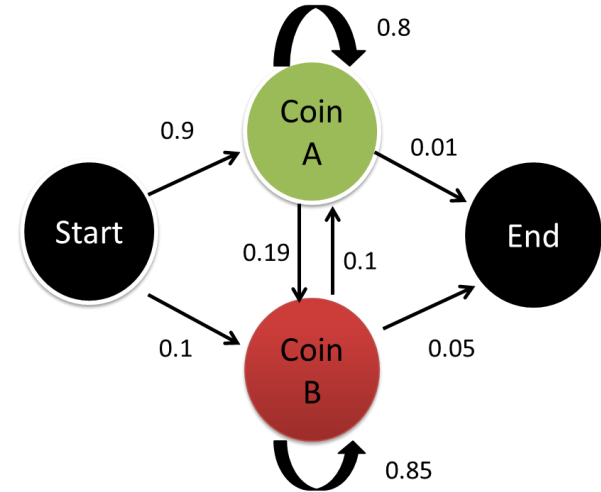


Let $f_j(i) = \Pr(x_0, \dots, x_i, \pi_i = j)$

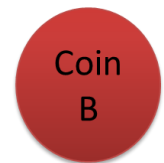
Initialization ($j=1 \dots N$) $f_j(0) = \pi_j e_j(x_0)$

Recursion ($i=1 \dots L$; $j = 1, \dots, N$) $f_j(i) = e_j(x_i) \sum_k (f_k(i-1) a_{kj})$

Probability of all the probable paths $P(x) = \sum_{\pi} P(x, \pi) = \sum_k f_k(L)$



H: 0.5
T: 0.5



H: 0.2
T: 0.8



- **O= HHTHHTTTHT**
- **argmax(P(O, Q, λ))**

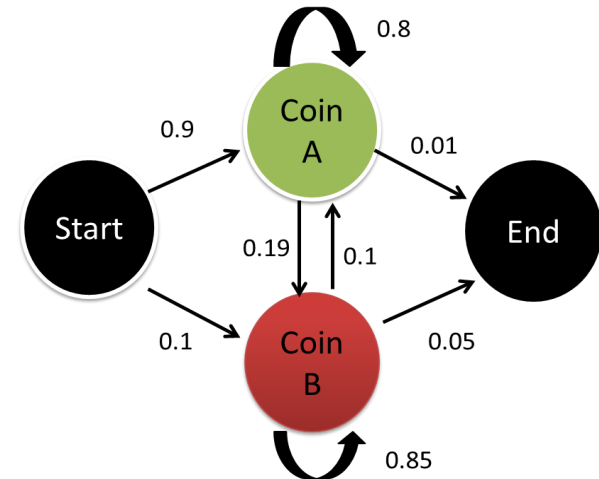
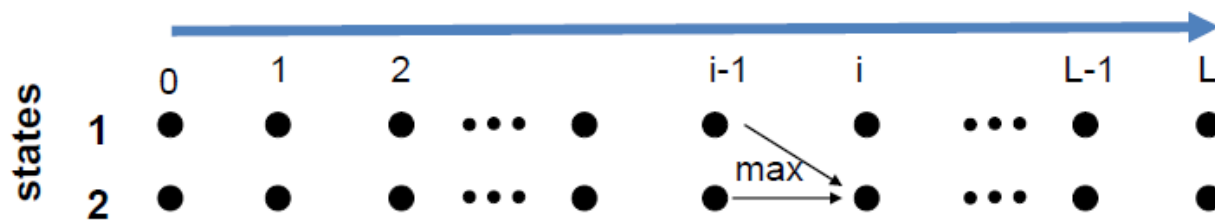
Problem 2: Given the observation sequence $O=O_1O_2\dots O_T$, and a model $\lambda=\{A, B, \text{Init}\}$, how to choose a corresponding state sequence $Q=q_1q_2\dots q_T$, which is optimal in some meaningful sense..



Viterbi Algorithms

A -> A -> A -> A -> A -> B -> B -> B -> B -> B

	H	H	T	H	H	T	T	T	H	T	Emd
A	0.45	0.18	0.072	0.028	0.011	0.004	1.843	7.372	2.949	1.180	4.68 0e-6
B	0.02	0.01	0.027	4.652	1.109	1.751	1.191	8.097	1.376	9.360	



Let
$$f_j(i) = \max_{\{\pi_0, \dots, \pi_{i-1}\}} (\Pr(x_0, \dots, x_{i-1}, x_i, \pi_0, \dots, \pi_{i-1}, \pi_i = j))$$

Initialization (j=1...N)
$$f_j(0) = \pi_j e_j(x_0)$$

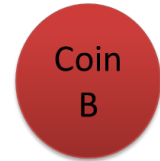
Recursion (i=1...L)

$$f_j(i) = e_j(x_i) \max_k (f_k(i-1) a_{kj});$$

$$ptr_j(i) = \arg \max_k (f_k(i-1) a_{kj}).$$



H: 0.5
T: 0.5



H: 0.2
T: 0.8



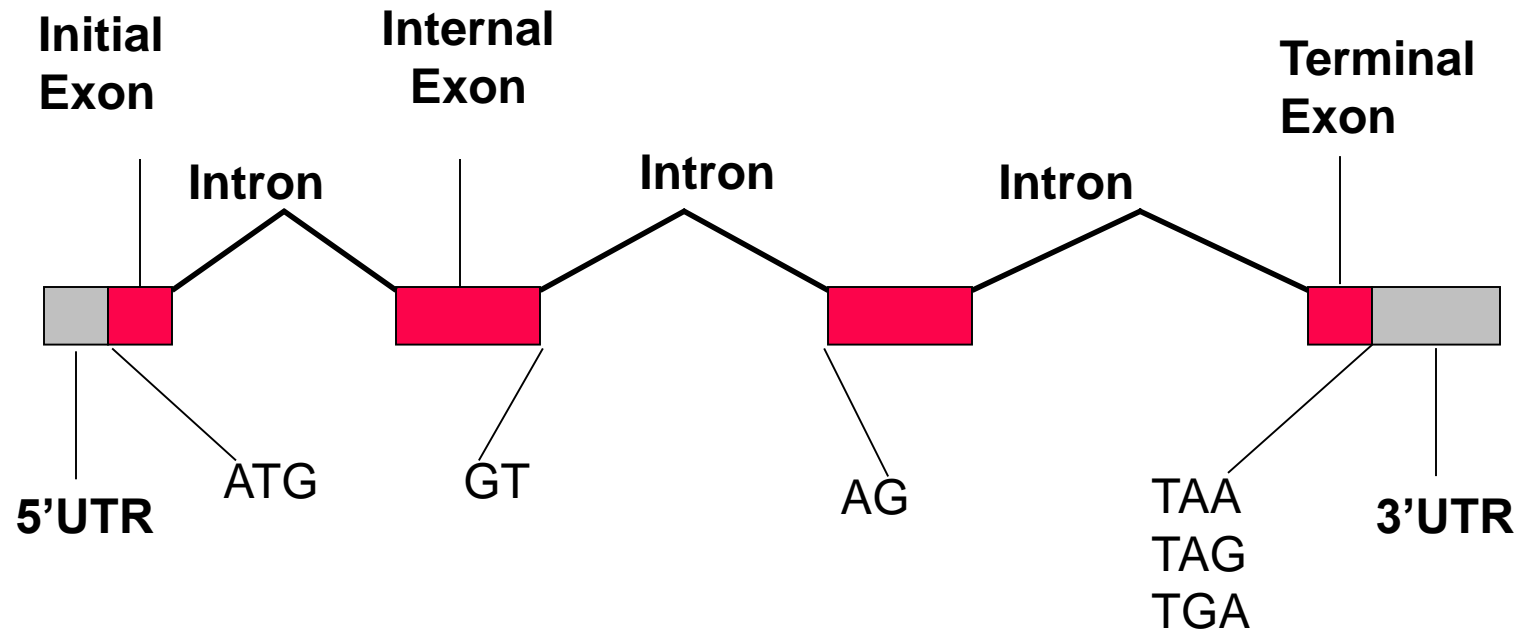
Problem 3. Model parameter estimation

See

- Rabiner, L.(1989) A Tutorial on Hidden Markov Models and Selected Applications in Speech Recognition. Proceedings of the IEEE, 77 (2) 257-286
- Rabiner, L., and Juang, Biing-Hwang, (1993), Fundamentals of Speech Recognition, Prentice Hall.



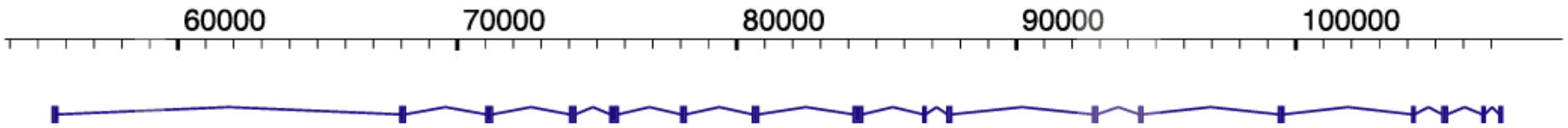
Gene Structure prediction with HMM



A gene is a highly structured region of DNA, it is a functional unit of inheritance.



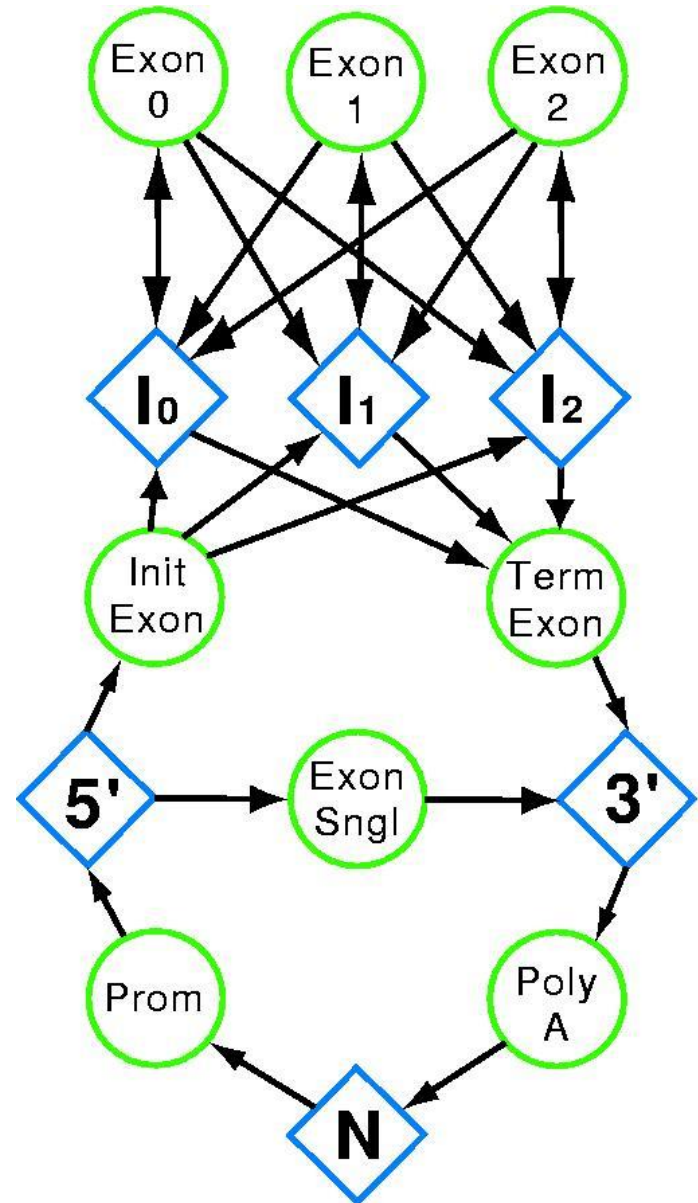
A Typical Human Gene Structure





Gene Prediction Model

- HMM (27 states)
- Each state
 - For a gene structure
- State-specific models (Generalized HMM)
 - Length distribution
 - Sequence content





Another example: Pair HMM for local alignment

